

# PULSE METER MP5W SERIES

MANUAL



Thank you very much for selecting Autonics products.  
For your safety, please read the following before using.

## Caution for your safety

※Please keep these instructions and review them before using this unit.
※Please observe the cautions that follow;
<b>Warning</b> Serious injury may result if instructions are not followed.
<b>Caution</b> Product may be damaged, or injury may result if instructions are not followed.
※The following is an explanation of the symbols used in the operation manual. △caution:Injury or danger may occur under special conditions.

### Warning

- In case of using this unit with machinery(Ex: nuclear power control, medical equipment, ship, vehicle, train, airplane, combustion apparatus, safety device, crime/disaster prevention equipment, etc) which may cause damages to human life or property, it is required to install fail-safe device.

It may cause a fire, human injury or damage to property.

### It must be mounted on panel.

It may give an electric shock.

### Do not repair or check up when power on.

It may give an electric shock.

### Do not disassemble and modify this unit, when it requires.

If needs, please contact us.

It may give an electric shock and cause a fire.

### Please check the number of terminal when connect power line or measuring input.

It may cause a fire.

### Caution

#### 1. This unit shall not be used outdoors.

It might shorten the life cycle of the product or give an electric shock.

#### 2. When wire connection for power input and measuring input, the tightening strength for screw bolt on terminal block should be over than 0.74N·m~0.90N·m.

It may result in malfunction or fire due to contact failure.

#### 3. Please observe specification rating.

It might shorten the life cycle of the product and cause a fire.

#### 4. Do not use the load beyond rated switching capacity of Relay contact.

It may cause insulation failure, contact melt, contact failure, relay broken, fire etc.

#### 5. In cleaning the unit, do not use water or an oil-based detergent.

It might cause an electric shock or fire that will result in damage to this product.

#### 6. Do not use this unit at place where there are flammable or explosive gas, humidity, direct ray the sun, radiant heat, vibration, impact etc.

It may cause a fire or explosion.

#### 7. Do not inflow dust or wire dregs into inside of this unit.

It may cause a fire or mechanical trouble.

#### 8. Please connect properly after checking the polarity of measuring terminals.

It may cause a fire or explosion.

※The above specification are changeable without notice anytime.

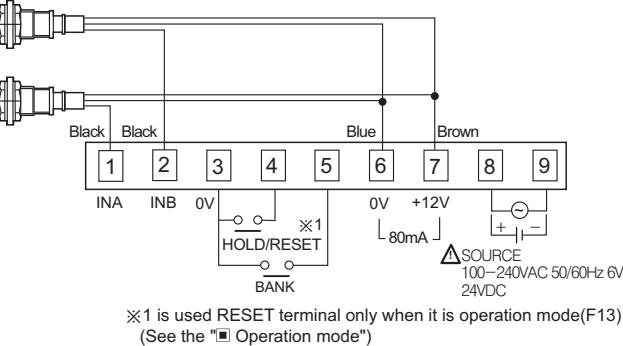
## Ordering information

MP 5 W - 4 N

Main output N	Main output (Comparative value output)	Sub output (Display value output)
A	Indicator	-
1	Relay five-stage(H, GO, L, LL)	-
2	NPN open collector quintuple output	BCD Dynamic
3	PNP open collector quintuple output	BCD Dynamic
4	NPN open collector quintuple output	PV transmission output (DC4-50mA)
5	PNP open collector quintuple output	PV transmission output (DC4-50mA)
6	NPN open collector quintuple output	Low speed serial output
7	PNP open collector quintuple output	Low speed serial output
8	NPN open collector quintuple output	RS485 communication
9	PNP open collector quintuple output	RS485 communication
Power supply	2	24VDC
Size	4	100~240VAC 50/60Hz
Digit	W	DIN W96 X H48mm
Item	5	99999(5 Digit)
	MP	Pulse meter
		※PNP open collector output: Option

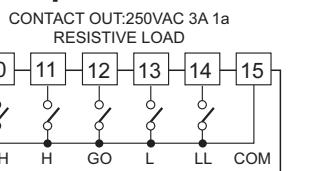
## Connections

### Main terminal block

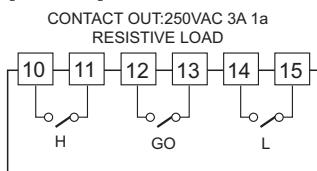


### Sub(option) terminal block

#### RELAY(Five-stage) output [MP5W-4A]

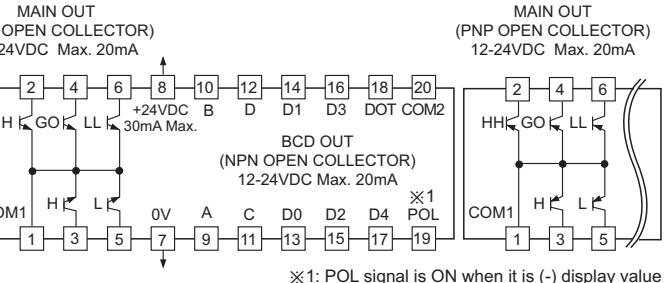


#### RELAY(Three-stage) output [MP5W-41]

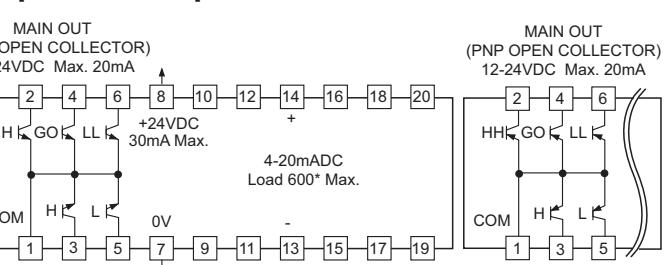


### Sub(option) output connector

#### NPN/PNP open collector output + BCD output [MP5W-42/MP5W-43]

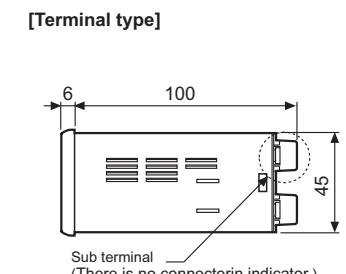
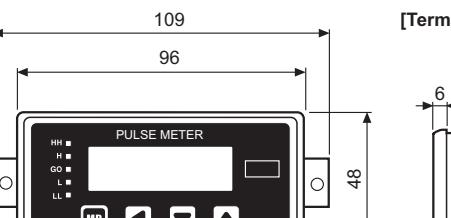


#### NPN/PNP open collector output + PV transmission(4-20mAADC) output[MP5W-44/MP5W-45]

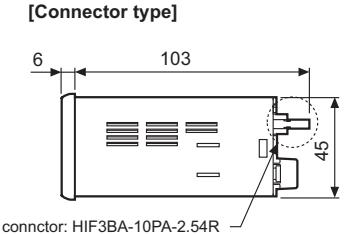
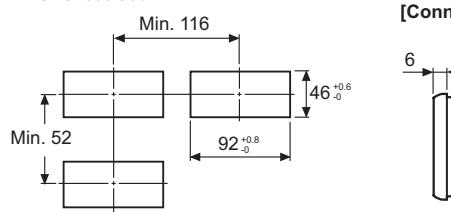


## Dimensions

(Unit:mm)

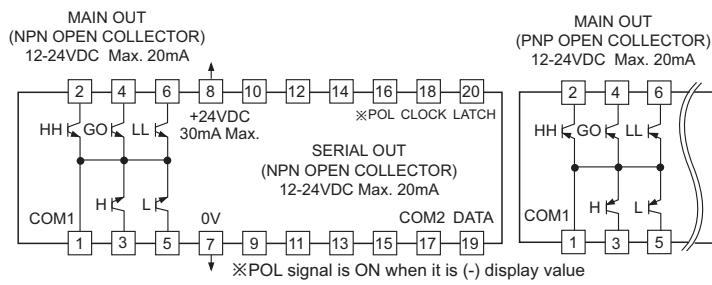


### Panel cut-out

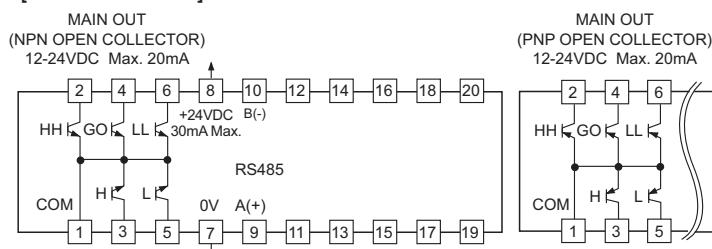


Hirose connector: HIF3BA-10PA-2.54R  
(There is no connector in indicator.)

### NPN/PNP open collector output + Low speed serial output[MP5W-46/MP5W-47]



### NPN / PNP open collector output + RS485 communication output [MP5W-48/MP5W-49]



## Input/Output

### Input specification

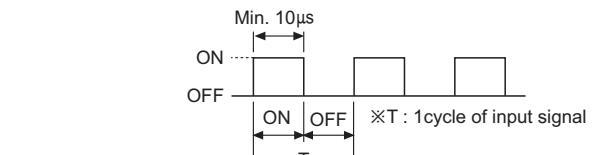
#### 1. Input signal

(1)Solid state input

①Input frequency: 50kHz(Max.)

But, standard duty rate of input signal is 1:1, ON/OFF pulse width should be each over 10μs.

②Input voltage Level : ON voltage → 4.5~24V, OFF voltage → 0~1.0V



#### 2. Relay contact input

①Input frequency: 45Hz(Max.)

But, ON/OFF pulse width should be each over 11ms.

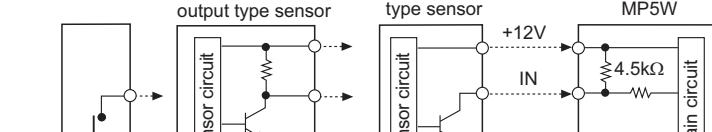
②Relay contact specification: Please use a contact that can switch reliably at 12VDC, 2mA min. of load current.

### Input type

MP5W has NPN input and PNP input and it is able to select it in Parameter 1 group.

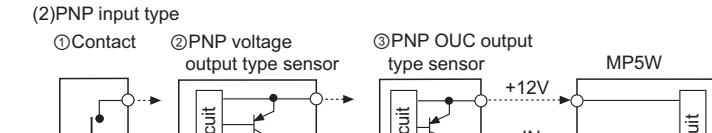
#### (1)NPN input type

①Contact



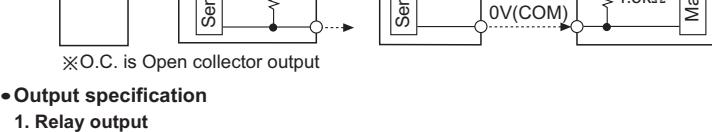
#### (2)PNP input type

①Contact



#### ③NPN O.C. output type sensor

④PNP OUC output type sensor



### Output specification

#### 1. Relay output

①Output : Comparative or alarm output(See the [ ] Output mode")

②Output method : Relay

③Contact capacity : 250VAC 3A resistive load

④Life cycle : Mechanical-20million times(Switch times 180 times/min.) Electrical-Min.100,000 times(3A 250VAC at resistive load) (Switch times : 20 times/min.)

#### 2. TR output

①Output : Comparative or alarm output(See the [ ] Output mode")

②Output method : NPN / PNP Open collector

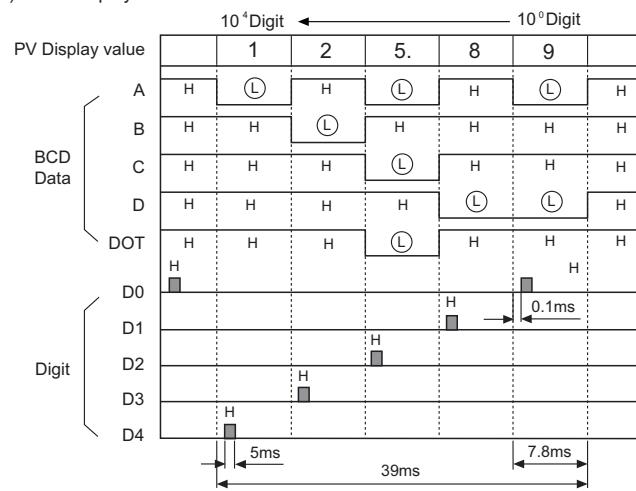
③Rated load voltage : 12-24VDC

④Max. load current : 20mA

### 3. BCD Dynamic output

- ① Output: Display value
- ② Output signal: BCD Data(A, B, C, D, DOT) ← A: Lowest bit, Dot: Highest bit  
Digit Data(D0, D1, D2, D3, D4) ← D0: Lowest digit, D4: Highest digit
- ③ Output type: NPN Open Collector
- ④ Rated load voltage: 12-24VDC
- ⑤ Max. load current: 20mA

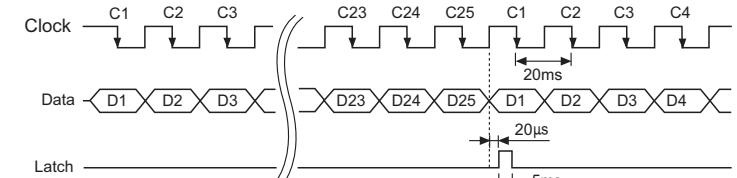
Ex) When display value is 125.89



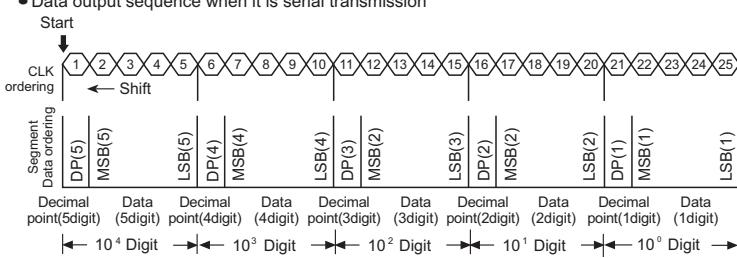
### 4. Low speed serial output

- ① Output: Display value
- ② Output signal: Clock, Data, Latch
- ③ Clock cycle: 50Hz
- ④ Output Clock bit: 25 bit
- ⑤ Output Data bit: 25 bit
- ⑥ Output form: NPN Open Collector
- ⑦ Rated load voltage: 12-24VDC
- ⑧ Max. load current: 20mA

#### • Serial transmission time diagram



#### • Data output sequence when it is serial transmission



### 5. PV transmission output(4-20mAADC)

- ① Application : To transmit the measured value
- ② Function : This function is to transmit 4-20mA converted from measured display value between High limit output(FS-H) and Low limit(FS-L).
- ③ Range of High/Low limit output setting
  - High limit setting range(FS-H): From min. to max within range of measurement
  - Low limit setting range(FS-L): From min. to max within range of measurement (FS-H should be over "1" bigger than FS-L)
- ④ Resistive load : Max. 600Ω
- ⑤ Resolution : 8000 division

If set FS-L and FS-H in certain section, the output will be 4-20mAADC.

Resolution between FS-L and FS-H is 8000, therefore if display value is narrower than 8,000 the resolution will be low.

### 6. RS485 communication output

- ① Address: 0 ~ 99 address(32 channel)
- ② Transmission speed(Baud rate): 2400/4800/9600 bps
- ③ Transmission code: ASCII
- ④ Parity Bit: No
- ⑤ Data Bit: 8 Bit
- ⑥ Stop Bit: 1 Bit
- ⑦ Communication items
  - MP5W ← PC: Comparative value of each bank data, Prescale value and Peak value, RESET control
  - MP5W → PC: Comparative value of each bank data, Prescale value and Peak value, Display value

## ■ Operation mode

- Select operation mode from **mode**(mode) of Parameter 1 group.
- There are 13 kinds of operation mode in this unit.
- Mode F1(Frequency/Number of revolution/Speed)
 

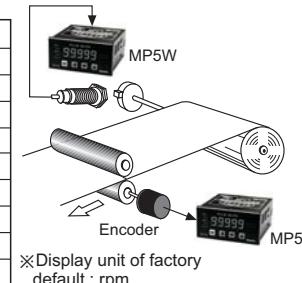
This mode is to display calculated frequency or number of revolution, speed by measuring frequency of input A.

  - 1) Frequency(Hz) =  $f \times \alpha$  ( $\alpha = 1[\text{sec}]$ )
  - 2) Number of revolution(rpm) =  $f \times \alpha$  ( $\alpha = 60[\text{sec}]$ )
  - 3) Speed(m/min) =  $f \times \alpha$  ( $\alpha = 60L[\text{sec}]$ )

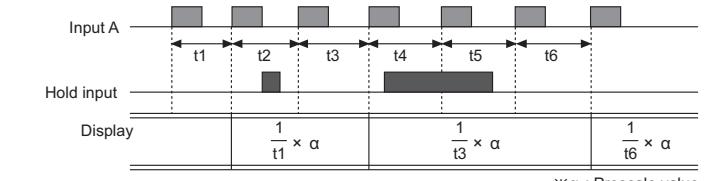
※ L = The length of conveyor moved for 1 pulse cycle[m]

#### • Display value and display unit

Display value	Display unit	$\alpha$ (Prescale value)
Frequency	Hz	1
	kHz	0.001
Number of revolution	rps	1
	rpm	60
Speed	mm / sec	1,000L
	cm / sec	100L
	m / sec	L
	m / min	60L
	km / hour	3.6L



#### • Time chart

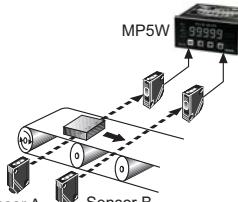


#### • Mode F2(Passing speed)

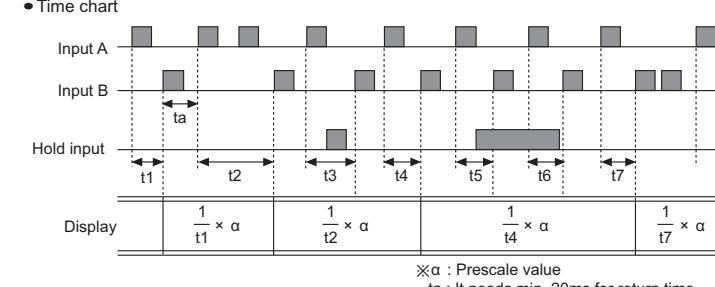
- It displays the passing speed between ON of input A and ON of input B.  
Passing speed(V) =  $f \times \alpha$  ( $\alpha = L[\text{m}]$ )  
※ f : This is reciprocal number of the time between ON of input A and ON of input B  
L : The distance between input A and input B[m]

#### • Display value and display unit

Display value	Display unit	$\alpha$ (Prescale value)
Passing speed	mm / sec	1,000L
	cm / sec	100L
	m / sec	L
	m / min	60L
	km / hour	3.6L



#### • Time chart

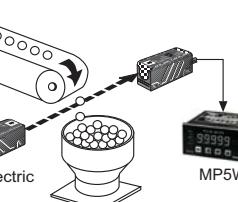


#### • Mode F3(Cycle)

- It displays the time from when input A is ON to the next ON of input A.  
Cycle(T) = t

#### • Display value and display unit

Display value	Display unit	
Cycle	SEC	MIN
	999.99sec.	999.99min.
	9999.9sec.	9999.9min.
	99min	99hour
	59.9sec.	59.9min.
	9hour 59min.	99hour 59min.
	59sec.	59min.
	99999sec.	99999min.



- Set the display unit at the **t.un**(Time unit) of Parameter 2.
- Display unit of factory default : 999.99sec.
- Time chart
 

Input A is ON at t1, t2, t3, t4, t5, t6. Hold input is ON at t1. Display shows the time intervals t1, t3, t5 multiplied by the prescale value alpha.
- t1, t2, t3, t4, t5, t6 should be over 20ms then able to measure.

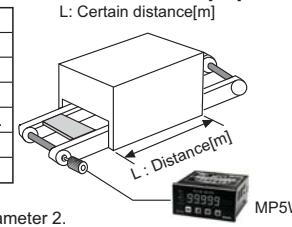
#### • Mode F4(Passing time)

- It displays the passing time of certain distance as measuring the time between ON and the next ON of Input A.

$$\text{Passing time}[sec] = t \times \alpha \quad (\alpha = \frac{L[m]}{\text{Moving distance within 1pulse cycle}[m]})$$

#### • Display value and display unit

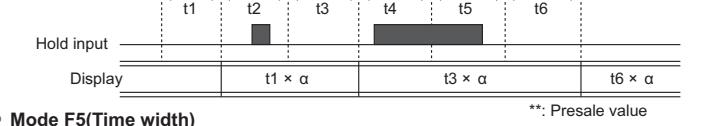
Display value	Display unit	
Passing time	SEC	MIN
	999.99sec.	999.99min.
	9999.9sec.	9999.9min.
	99hour 59.sec.	99hour 59min.
	9hour 59min. 59sec.	99hour 59min.
	99999sec.	99999min.



※ Display unit of factory default : 999.99sec.

※ Set the display unit at the **t.un**(Time unit) of Parameter 2.

#### • Time chart



#### • Mode F5(Time width)

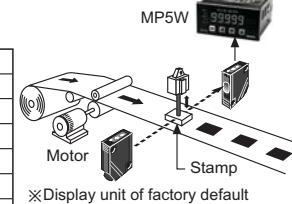
- It displays the ON time of input A.

$$\text{Time width}[T] = t$$

※ t : ON measurement time of input A[sec]

#### • Display value and display unit

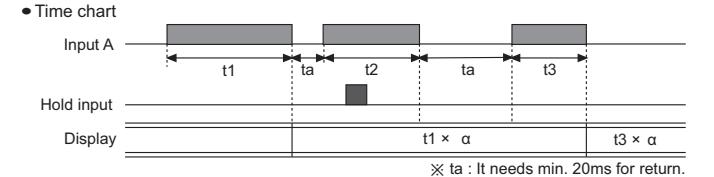
Display value	Display unit	
Time width	SEC	MIN
	999.99sec.	999.99min.
	9999.9sec.	9999.9min.
	99hour 59.sec.	99hour 59min.
	9hour 59min. 59sec.	99hour 59min.
	99999sec.	99999min.



※ Display unit of factory default : 999.99sec.

※ Set the display unit at the **t.un**(Time unit) of parameter 2.

#### • Time chart



#### • Mode F6(Time interval)

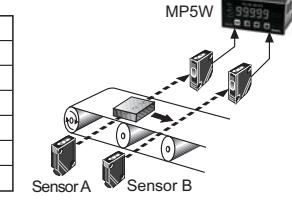
- It displays the time from input A is ON to input B is ON.

$$\text{Time difference}(T) = t(t_a to t_b)$$

※ t(ta to tb): The measurement time from input A is ON to input B is ON[sec]

#### • Display value and display unit

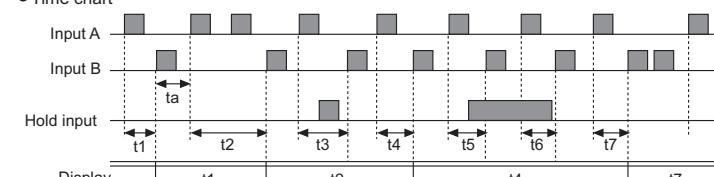
Display value	Display unit	
Time interval	SEC	MIN
	999.99sec.	999.99min.
	9999.9sec.	9999.9min.
	99hour 59.sec.	99hour 59min.
	9hour 59min. 59sec.	99hour 59min.
	99999sec.	99999min.



※ Display unit of factory default : 999.99sec.

※ Display unit can be set at **t.un**(Time unit) of Parameter 2.

#### • Time chart



#### • Mode F7(Absolute rate)

- It displays how many percentage(%) faster or late, speed, volume etc. of Input B against input A)

$$\text{Absolute rate} = (\text{Input B} / \text{Input A}) \times 100\%$$

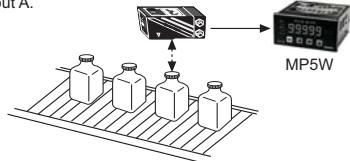
$$\text{Absolute rate} = \frac{\text{Frequency of input B}[Hz] \times \alpha_B}{\text{Frequency of input A}[Hz] \times \alpha_A} \times 100\% [ ]$$

#### • Display value and display unit

Display value	Display unit	

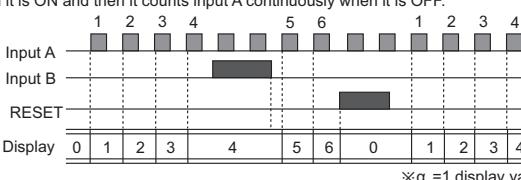
<tbl\_r cells="3" ix="1" maxcspan="1" maxrspan="1" used

- Mode F13(Integration)**  
It displays the counting value against pulses of Input A.  
Integration =  $P \times \alpha$   
※P: Pulse number of input A,  $\alpha$  : Prescale value



- Display value and display unit**
- |               |              |
|---------------|--------------|
| Display value | Display unit |
| Integration   | Quantity(EA) |

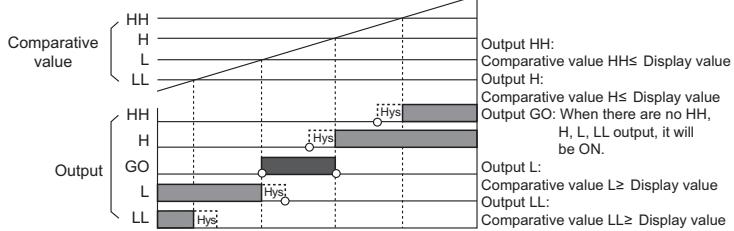
- Operation and Time chart**  
① It counts the number of input A pulse.  
② As input B is an enable input signal it stops the counting and display value of input A when it is ON and then it counts input A continuously when it is OFF.



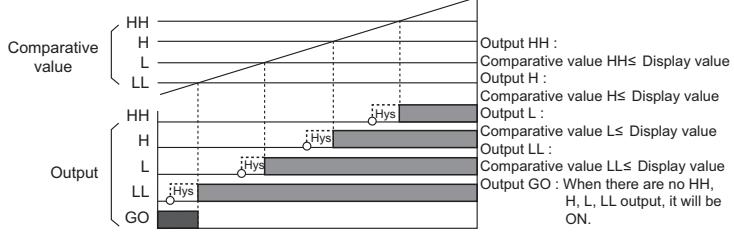
## Output mode

- Select output mode in **out-t**(output type) of Parameter1 group.
- There are 5 stages output(HH, H, GO, L, LL) and 3 stage output(H, GO, L).
- There are 6 kinds of output mode such as S(Standard) output mode, H(High) output mode, L(Low) output mode, B(Block) output mode, I(One shot)output mode, F(Deviation) output mode.
- Comparative value(HH, H, L, LL) can be set as LL<L<HH in B output mode and the other outputs can be operated separately in output( S.H, L, I) mode regardless of comparative(HH, H, L, LL) set value.

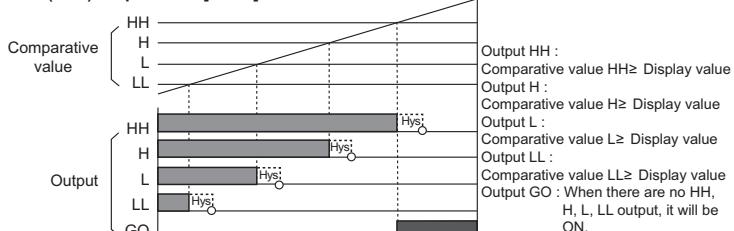
### S(Standard) output mode[StRd]



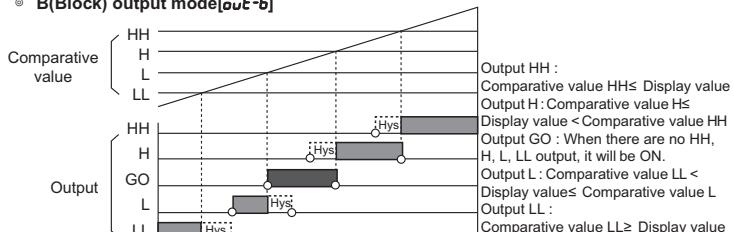
### H(High) output mode[out-h]



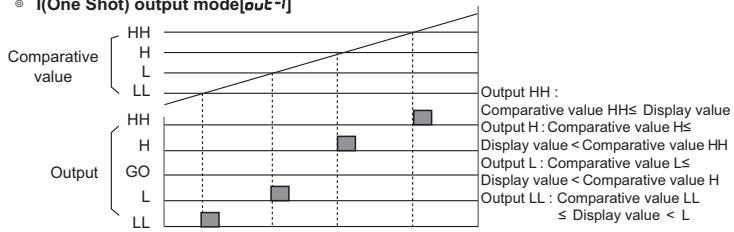
### L(Low) output mode[out-L]



### B(Block) output mode[out-b]



### I(One Shot) output mode[out-i]

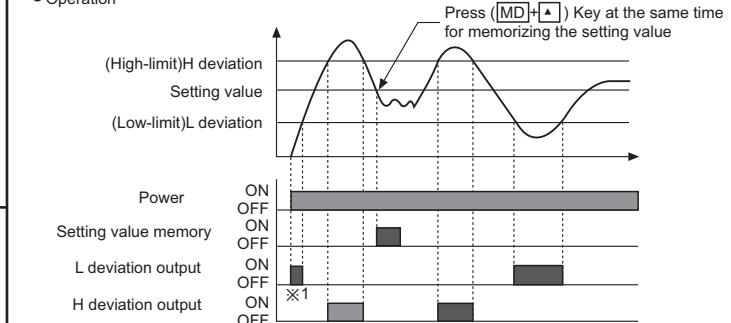


※There is no GO output in output I mode.  
※One Shot(■) output time has been fixed 0.3sec.  
※There is no Hysteresis in (One shot) comparative output mode.

### F(Deflection) output mode[out-f]

This function is to memorize the setting value and provide outputs when it exceeds the deviation of H, L.

- The setting value memory: Memorize the current display value as the setting value by pressing(**MD** + ▲) key in front.
- Display the setting value: Check the memorized the setting value by (▲) key.  
(Display the memorized setting value for pressing ▲ key continuously.)
- Deviation setting : Set H, L deviation by setting value.  
(The set deviation will be memorized until set the next deviation again when power off.)
- Deviation setting range : 0.0001 to 99999(The setting range will be changed by decimal point setting parameter. If set decimal point as 0000.0, the setting range will be 0.1 to 9999.9.)
- Operation



※1: When select the comparative output limit function, output will not be come.  
※2: Output position may different from above graph as output coming under assuming the setting value memory is before the setting value memory point on above graph.  
※There are no HH, GO, LL outputs in F output mode.  
※Even though you set the deviation as "0(Zero)", it will actually work as setting "1".

## Operation chart by each Parameter group

- The display parameter are different by each operation mode, please see "Parameter".
- When select the operation mode, the parameter will be displayed.  
X: When select the operation mode, the parameter will not be displayed.

### Parameter 0 group

Parameter 0	Sub mode	F1	F2	F3	F4	F5	F6	F7	F8	F9	F10	F11	F12	F13
PSt.hh		●	○	○	●	○	○	●	○	○	●	○	●	○
PSt.h		●	○	○	●	○	○	●	○	○	●	○	●	○
PSt.L		●	○	○	●	○	○	●	○	○	●	○	●	○
PSt.LL		●	○	○	●	○	○	●	○	○	●	○	●	○
h.PEt		●	○	○	●	○	○	●	○	○	●	○	●	X
L.PEt		●	○	○	●	○	○	●	○	○	●	○	●	X

### Parameter 1 group

Parameter 1	Sub mode	F1	F2	F3	F4	F5	F6	F7	F8	F9	F10	F11	F12	F13
nodeE		●	○	○	●	○	○	●	○	○	●	○	●	○
in-R		●	○	○	●	○	○	●	○	○	●	○	●	○
in-b		X	○	X	X	○	●	○	○	●	*	*	*	*
out-t		●	○	○	●	○	○	●	○	○	●	○	●	X
hYS		●	X	X	X	X	●	○	○	X	X	X	X	X
GuRd		●	○	○	●	○	○	●	○	○	●	○	●	X
FdEFY		●	○	○	●	○	○	●	○	○	●	○	●	X
StRd		●	○	○	●	○	○	●	○	○	●	○	●	X
AutoR		●	X	X	●	X	X	●	○	●	X	X	X	X
AutoB		X	X	X	X	X	●	○	●	X	X	X	X	X
NEno		X	X	X	X	X	X	X	X	X	X	X	X	X

\*": in-b sensor will be set as nPn.h.F or PnP.h.F in mode F11, F12, F13.

### Parameter 2 group

Parameter 2	Sub mode	F1	F2	F3	F4	F5	F6	F7	F8	F9	F10	F11	F12	F13
PbPEt		●	○	○	●	○	○	●	○	○	●	○	●	○
dot		●	○	X	X	X	●	○	○	●	○	●	○	●
tunt		X	X	●	○	●	○	X	X	X	X	X	X	X
PSt.hh		●	○	○	●	○	○	●	○	○	●	○	●	○
PSt.h		●	○	○	●	○	○	●	○	○	●	○	●	○
PSt.L		●	○	○	●	○	○	●	○	○	●	○	●	○
PSt.LL		●	○	○	●	○	○	●	○	○	●	○	●	○
PSCEH		●	○	X	○	X	●	○	○	●	○	●	○	●
PSCRY		●	○	X	●	X	●	○	○	●	○	●	○	●
PSCbH		X	X	X	X	X	●	○	●	○	X	X	X	X
PSCbY		X	X	X	X	X	●	○	●	○	X	X	X	X
dSPt		●	X	X	X	X	●	○	●	○	X	X	X	X

\*1: PSt.H, PSt.Y are displayed in mode F1, F2, F4, F11, F12, F13.

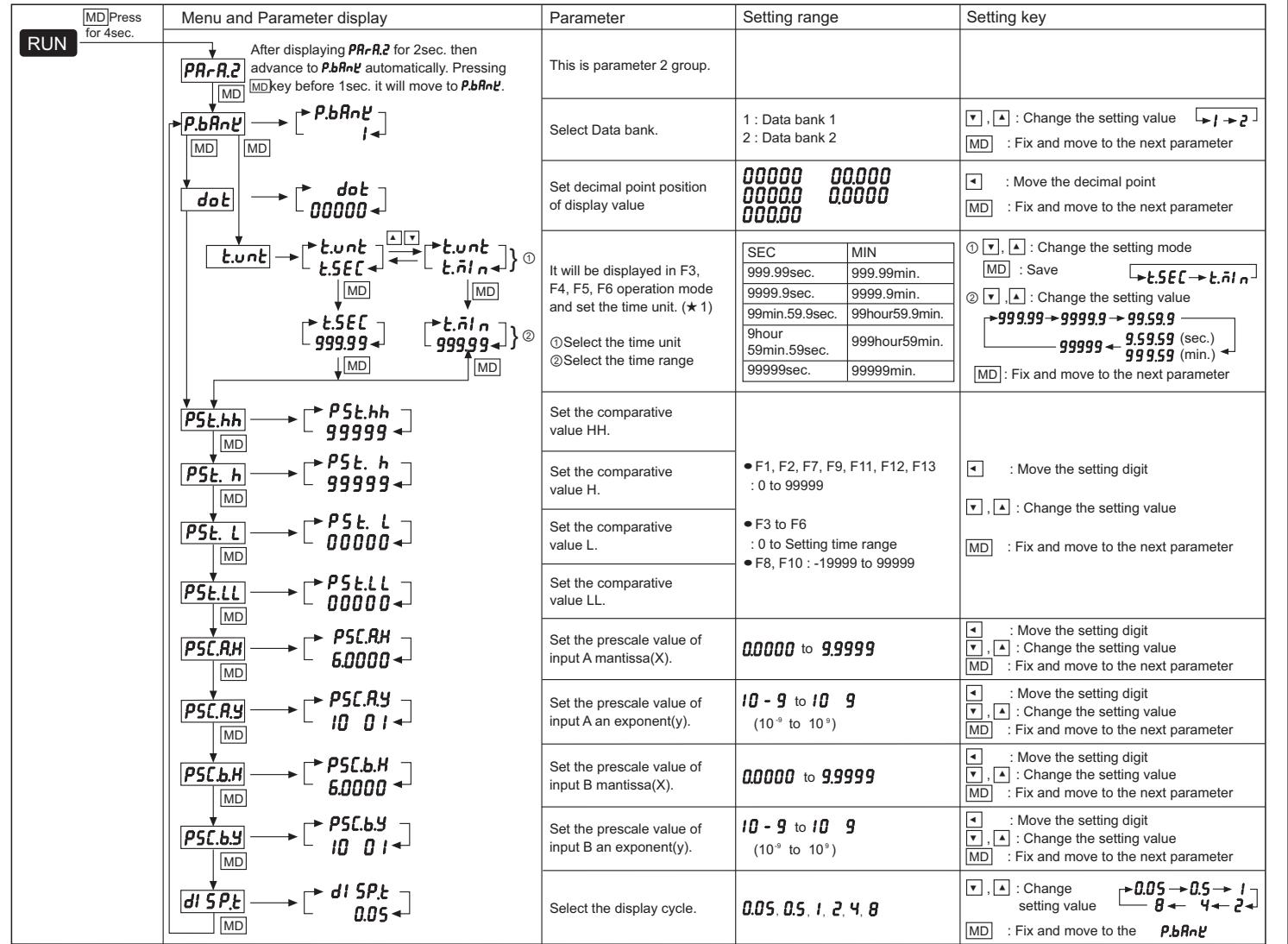
### Parameter 3 group

Parameter 3	Sub mode	F1	F2	F3	F4	F5	F6	F7	F8	F9	F10	F11	F12	F13
F5-h														
F5-l														
Rdr														
bPS														
rEnat														
LoC		●	○	○	●	○	○	●	○	○	●	○	●	○

### Monitoring delay function operation chart by each output mode

out-t	StRd	out-h	out-L	out-b	out-I	out-F
Comparative output adjustment function.	●	X	X	●	X	●
Starting correction timer function	●	●	●</			

## • Parameter 2 group



\*It will enter into parameter 2 if pressing [MD] key for 4sec in RUN mode

\*★1) It will be displayed in F3, F4, F5, F6 operation mode only and enable to select the time until as sec.[t.SEC] or min.[t.HH] in t.unL parameter.

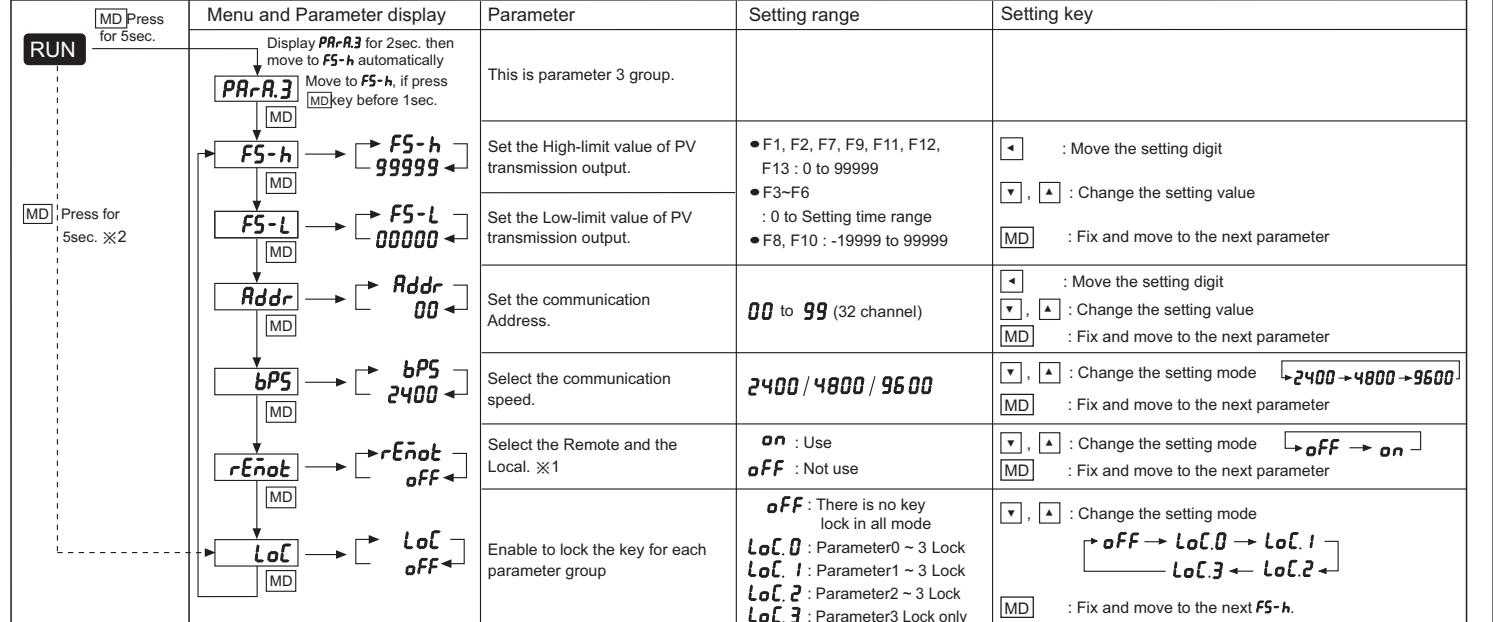
Select the time range after selecting the time unit as sec.[t.SEC] or min.[t.HH].

\*If press [MD] key for over 2 sec. in every setting mode, data will be set and return to RUN.

\*When enter into the parameter 2 group, the parameter name and data value will flicker by cycle(1sec.). Then to move the setting digit by □ key and change the setting value by ▵ ▷ key.

\*The fixed data value set by user in each parameter will flicker by cycle(1sec.) and move to the next parameter by pressing [MD] key.

## • Parameter 3 group



\*It will enter into parameter 3 if pressing [MD] key for 5sec. in RUN mode.

\*1: It is enable to set the remote or local function in communication output type. When select the remote[rEnot] function, the front keys are disabled.

\*2: Pressing [MD] key at parameter 3, it will enter into FS-h → Addr(option function), LoL(indication type only).

\*If press [MD] key for over 2 sec. in every setting mode, data will be set and return to RUN.

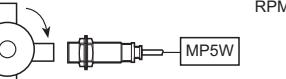
\*When entering into the parameter 3 group, the parameter name and data value will flicker by cycle(1sec.). Then move the setting digit by □ key and change the setting value by ▵ ▷ key.

\*The fixed data value set by user in each parameter will flicker by cycle(1sec.) and move to the next parameter by pressing [MD] key.

## ■ Function

### • Prescale function

This prescale function allows you to multiply the number of pulse or pulse length by a variable ( $\alpha \times 10^x$ ) then display a specific unit or a certain double number. It will display frequency or RPM from prescale value( $\alpha$ ) by measuring the input A frequency. For example, the prescale value when need to display the RPM as below.



$$\begin{aligned} \text{RPM} &= f \times \alpha \\ &= f \times 60 \times 1/N \quad \text{×f: Input pulse} \\ &= f \times 60 \times 1/4 \quad \text{(Frequency) per sec.} \\ &= f \times 60 \times 0.25 \quad \text{×α: Prescale value} \\ &= f \times 15 (\alpha = 15) \quad \text{×N: Pulse number per} \\ &\quad \quad \quad 1 \text{ revolution} \end{aligned}$$

### • How to set prescale value( $\alpha = 15$ )

Set prescale value separating as a mantissa(X) and an exponent(Y) at **PSC.RH**, **PSC.RY** (or **PSC.b.H**, **PSC.b.Y**). For example, prescale value(\*)=15, a mantissa(X):1.5000, an exponent(Y): 01. Or if set  $\alpha$  value as **PSC.RH**=0.1500, **PSC.RY**=02 then also get the same display value.

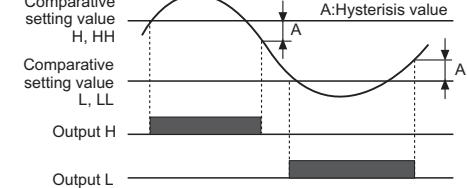
### • Monitoring function

This function is to save High Peak value(**HPEH**) or Low Peak value(**LPEH**) against display value. • User can check saved value in Parameter 0 group. And High Peak value(**HPEH**) or Low Peak value(**LPEH**) will be continuously saved during checking.

### • See Parameter 0 for Reset.

### • Hysteresis function

Set the Hysteresis value(A) for comparative setting value in order to prevent unstable operation due to output going ON/OFF frequently.



DOT position	Setting range
00000	0000 to 9999
00000	000.0 to 999.9
000.0	00.00 to 99.99
00.00	0.0000 to 9.9999
0.0000	0.0000 to 0.9999

\*You are able to set "0", but when set "0", the actual operation will be as "1".

\*The initial setting value is 0001.

\*You are able to set in the Parameter 1 group.

### • Monitoring delay times function

This function is for the stable control to limit L, LL outputs until certain output is come or to limit all outputs while the equipment is reaching a stable status against various change of input such as the starting current when the motor is running after power on. There are the starting correction timer function and comparative output limit function in the monitoring delay function.

### • The starting correction timer function

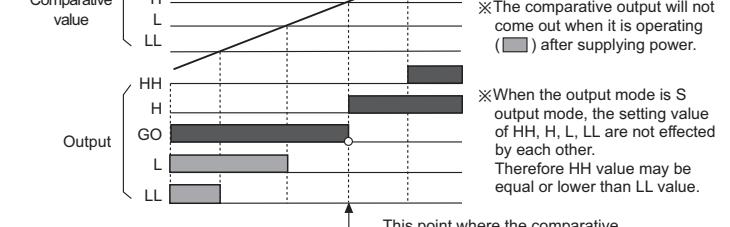
This function is to make the output not come out during the setting time. (Time setting range 0.0 to 99.9sec.)

### • Comparative output limit function(LL, L output limit function)

Applicable output mode: S,B,F mode(See \*\*Output mode\*)

This function is to limit the LL, L output before H or HH output.

### 1) The output mode is S output mode

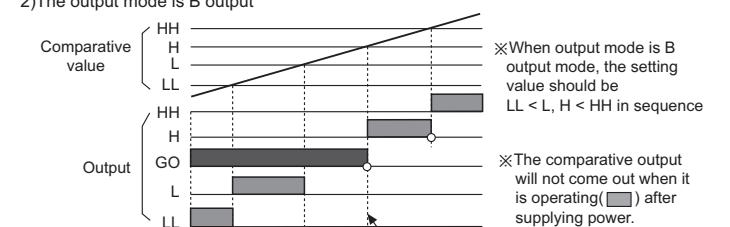


\*The comparative output will not come out when it is operating (solid bar) after supplying power.

\*When the output mode is S output mode, the setting value of HH, H, L, LL are not effected by each other.

Therefore HH value may be equal or lower than LL value.

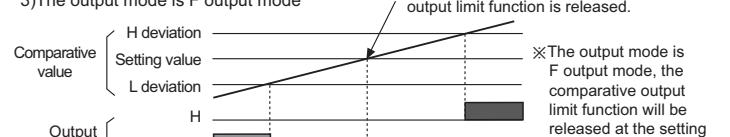
### 2) The output mode is B output



\*When output mode is B output mode, the setting value should be LL < L, H < HH in sequence

\*The comparative output will not come out when it is operating(solid bar) after supplying power.

### 3) The output mode is F output mode



\*The output mode is F output mode, the comparative output limit function will be released at the setting value(Standard setting).

### • Auto-Zero time setting function

When you know the interval of input signal, Auto-zero time should be set as a little bit longer than that interval of input signal. If there is no pulse input within setting time(Auto-zero time), it regards as the input signal is cut off then make the value as "00000" forcibly. Note that the Auto-zero time setting should be longer than the narrowest interval of input pulse. Otherwise it may be difficult to make the display value as "00000".

### • Auto-zero time setting range(0.1 to 999.9sec)

• When the display value is "00000", each output will respond to how it was programmed for "0".

## • Lock setting function

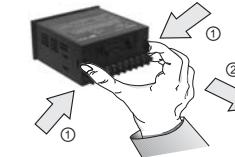
This function is to set the enable or disable of each Parameter and mode changes in MP5W.

Parameter	Parameter 0 group	Parameter 1 group	Parameter 2 group	Parameter 3 group
oFF	-	-	-	-
LoC.0	●	●	●	●
LoC.1	-	●	●	●
LoC.2	-	-	●	●
LoC.3	-	-	-	●

● - : Unlock, ● : Lock

※Lock setting is available in Parameter 3 group.

### • Case detachment



Please turn off the power before detaching the case.  
Push the side locks to direction ① and then pull out to direction ②.

### • Inner hardware Lock setting function

This function is to lock **LoC** in Parameter 3 group by Inner hardware Lock mode in order to prevent wrong setting.

Pin	LoC Mode	Remark
h0 (Hardware Lock0)		Check: ○, Change: ○ Factory default
h1 (Hardware Lock1)		Check: ○, Change: ×
h2 (Hardware Lock2)		Check: ×, Change: ×

\*Setting pin for Lock setting is located on internal PCB.

### • Display cycle selection function

This function is to change the display cycle in range of 0.05/0.5/1/2/4/8 sec., and displays the average value of measuring value for the setting cycle.

### • Time unit selection function

Enable to display PV value with firmed time unit in range of various time.

- Time unit selection function can be set in parameter 2 group.
- Applicable mode : Mode 3 to 6

\*There is no DOT setting mode when set the time unit display function.

### • Data Bank switching function

This function is to use the values by switching Data Bank 1, 2 after registering comparative setting value and prescale value into Data Bank1 and Data Bank2.

- When the 3 and 5 terminals are open circuited, the comparative value and prescale of Data Bank 1 will be used.
- When the 3 and 5 terminals are short-circuited, the comparative value and prescale of Data Bank 2 will be used.
- After selecting the Data Bank for saving the comparative setting value and prescale value, set the comparative setting value and prescale value then it will be saved at Data Bank.

### • Factory default

- Parameter 1 group

Mode	Setting value	Mode	Setting value	Mode	Setting value




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